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THE LARGE SAMPLE CORRESPONDENCE BETWEEN CLASSICAL HYPOTHESIS TESTS AND BAYESIAN POSTERIOR ODDS TESTS

By DONALD W. K. ANDREWS¹

This paper establishes a correspondence in large samples between classical hypothesis tests and Bayesian posterior odds tests for models without trends. More specifically, tests of point null hypotheses and one- or two-sided alternatives are considered (where nuisance parameters may be present under both hypotheses). It is shown that for certain priors the Bayesian posterior odds test is equivalent in large samples to classical Wald, Lagrange multiplier, and likelihood ratio tests for some significance level and vice versa. The priors considered under the alternative hypothesis are taken to shrink to the null hypothesis at rate $n^{-1/2}$ as the sample size n increases.

KEYWORDS: Asymptotics, Bayesian, Bayes factor, classical, hypothesis test, likelihood ratio, posterior odds, prior.

1. INTRODUCTION

THIS PAPER CONSIDERS LARGE SAMPLE APPROXIMATIONS to Bayesian posterior odds test statistics for models without trends. For certain priors that shrink to the null hypothesis as the sample size goes to infinity, the approximations turn out to be monotone functions of the standard Wald, Lagrange multiplier (LM), and likelihood ratio (LR) test statistics. In consequence, the posterior odds test for a given prior corresponds in large samples to a classical hypothesis test for some significance level α . In turn, a classical hypothesis test with given significance level α corresponds in large samples to a variety of Bayesian posterior odds tests based on different priors. Thus, the choice of significance level for classical tests is seen to be analogous to the choice of prior for Bayesian posterior odds tests and vice versa.

The results referred to above may be of interest to classical and Bayesian econometricians alike. In addition, Bayesian econometricians may find the approximations quite convenient from a computational perspective, because they eliminate high-dimensional integrations, especially with certain choices of priors. Bayesian econometricians also may find the approximations of interest because they illustrate certain robustness properties of posterior odds tests. The results show that posterior odds tests for a variety of different priors yield equivalent tests in large samples.

There is considerable literature on the relationship between classical hypothesis tests and Bayesian posterior odds tests. Some of this literature focuses on the question of whether a p value can be viewed as a posterior probability of the null hypothesis. In some cases where one is testing a one-sided null

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hypothesis against a one-sided alternative hypothesis concerning a scalar parameter, such an interpretation is possible (e.g., see Casella and R. L. Berger (1987), J. O. Berger (1985, pp. 147–148), DeGroot (1973), and Pratt (1965)). In other cases, notably those with a point null hypothesis and one- or two-sided alternatives, the interpretation of a p value as the posterior probability of the null hypothesis is not possible (e.g., see J. O. Berger (1985, pp. 148–151), J. O. Berger and Sellke (1987), and Edwards, Lindman, and Savage (1963)). On the other hand, for point null hypotheses, Hodges (1992) has constructed point alternatives for which the p value is approximately equal to the posterior probability of the null hypothesis.

In this paper, we consider point null hypotheses with one- or two-sided alternatives (and allow for nuisance parameters under the null and the alternative). We are interested in the correspondence between classical hypothesis tests and Bayesian posterior odds tests, but we do not focus on the question of whether a p value can be interpreted as a posterior probability of the null hypothesis. Rather, we ask the question of whether a Bayesian posterior odds test for some significance level. In a large sample sense, we find that the answer is yes for a variety of different shrinking priors.

Various results in the literature also are relevant to the question of whether a Bayesian posterior odds test is equivalent to some classical test for some significance level. A number of finite sample results show this for particular models and priors; see Jeffreys (1961, Chs. V, VI), Zellner and Siow (1979, 1980), and for further references Zellner (1984, Ch. 3.7, p. 285). In addition, there are some asymptotic results that are relevant, including those of Jeffreys (1961, pp. 246–7, 249–50), Lindley (1961), Schwarz (1978), Kass, Tierney, and Kadane (1988), Kass and Vaidyanathan (1992), and Phillips (1992). The relationship of our results to the latter asymptotic ones is discussed below (see Section 7).

In this paper, we also analyze classical and Bayesian tests that are designed to be impartial between the null hypothesis and a chosen alternative distribution. We find that the impartial classical and Bayesian tests are equivalent asymptotically for one-sided alternative hypotheses. For two-sided hypotheses, we find that they are not equivalent asymptotically, but are quite close to being so. We note that these results are established for models without trends. For example, they do not apply to tests of a unit root.

The remainder of this paper is organized as follows. Section 2 states the testing problem of interest and outlines the results of the paper. Section 3 specifies the parametric model under consideration and states various "high-level" assumptions that it is required to satisfy. These high-level assumptions include the assumptions that the normalized score function and sample information matrix satisfy a central limit theorem and law of large numbers, respectively, and that the maximum likelihood estimator is consistent. These assumptions are replaced by more primitive assumptions later in the paper. The high-level assumptions are employed, because they help to clarify the essential

aspects of the parametric model that are needed for the results of the paper. Section 4 specifies the prior distributions that are considered in the paper. Section 5 states the main results and discusses their implications. Section 6 provides primitive conditions for the assumptions of Section 3 for the case of stationary nonlinear models. Section 7 discusses related results in the literature. An Appendix provides proofs of the results stated in the paper.

All limits below are taken "as $T \to \infty$," where T is the sample size. We let $wp \to 1$ denote "with probability that goes to one as $T \to \infty$," ~ denote "has the same distribution as," and $\tilde{\pi}$ denote pi = 3.14...

2. THE PROBLEM OF INTEREST AND OUTLINE OF RESULTS

The testing problem considered here is the following: Suppose we have a parametric model indexed by a parameter $\theta \in \Theta \subset R$. The parameter θ is of the form $\theta = (\beta', \delta')'$, where $\beta \in R^p$, $\delta \in R^q$, and s = p + q. We are interested in testing the null hypothesis

(2.1)
$$H_0: \beta = 0.$$

In the classical testing scenario, H_0 is tested against the alternative hypothesis H_1 given by

$$(2.2) \qquad H_1: \beta \neq 0.$$

In a Bayesian scenario, the alternative hypothesis H_1 is that the parameter β has some distribution that is not pointmass at 0. For the case where p = 1, we also consider the one-sided alternative testing problem where the hypotheses are H_0 : $\beta = 0$ and H_1 : $\beta > 0$.

We note that, although (2.1) and (2.2) involve testing linear restrictions, the results given below apply more generally. One usually can reparameterize the model under consideration to convert nonlinear restrictions of the form H_0 : $h(\theta) = 0$ into linear restrictions of the form (2.1) in a transformed parameter space. The results given below can be applied with the transformed parameter space and then mapped back to the original parameter space. (For an alternative approach to posterior odds testing with nonlinear restrictions, see McCulloch and Rossi (1992).)

With classical methods, one can test the null hypothesis H_0 : $\beta = 0$ using a standard Wald, LM (score), or LR statistic given a significance level α . Such tests have well-known asymptotic optimality properties; e.g., see Wald (1943). Under suitable regularity conditions, these statistics have a nuisance parameter free asymptotic distribution under H_0 and an asymptotically valid critical value, $k_{p,\alpha}$, can be obtained given a significance level α .

Using Bayesian methods, one can carry out a posterior odds test of H_0 against H_1 . To do so one specifies a prior probability $\pi \in (0, 1)$ for the null hypothesis H_0 and prior distributions over the parameter values both under H_0 and under H_1 . If π is set equal to 1/2 (e.g., as advocated by Jeffreys (1961, pp. 246)), then the prior odds are even. In any event, the posterior odds statistic in favor of H_1 is given by the ratio of the posterior probability of H_1 to that of H_0 . A posterior odds test rejects H_0 if the posterior odds statistic (in favor of H_1) is greater than 1 and otherwise accepts H_0 .²

Let W_T , LM_T , and LR_T denote the standard Wald, LM, and LR statistics respectively. (The statistic LR_T equals -2 times the log of the likelihood ratio.) The main result of this paper is that for certain choices of prior, Q_{μ} , the posterior odds ratio is approximately equal to a monotone function of W_T , LM_T , or LR_T in large samples.

To define this monotone function, let S_p denote the unit sphere $\{v \in \mathbb{R}^p: \nu'\nu = 1\}$ for $p \ge 1$ and let S_1^+ denote the unit sphere in \mathbb{R}^+ , i.e., $S_1^+ = \{1\}$. Let \mathscr{I}_p generically denote one of the unit spheres S_p or S_1^+ . The unit sphere S_p arises with two-sided tests of the value of a *p*-dimensional vector β . The unit sphere S_1^+ arises with one-sided tests of the value of a scalar parameter β .

The posterior odds ratio in favor of H_1 is shown to be approximately equal to $PO(W_T, \mu)$, $PO(LM_T, \mu)$, and $PO(LR_T, \mu)$, where

(2.3)
$$PO(M,\mu) = \frac{1-\pi}{\pi} \int \exp(-r^2/2)g_p(Mr^2)d\mu(r)$$

for $M = W_T$, LM_T , or LR_T . Here, $\mu(\cdot)$ is a probability distribution on $R^+ = \{r \in R: r \ge 0\}$ that depends on the prior Q_{μ} and $g_p(\cdot)$ is a function defined by

$$(2.4) g_{\rho}(\kappa) = \int_{\mathscr{P}_{\rho}} \exp\left(|\kappa|^{1/2} \operatorname{sgn}(\kappa)\xi'\mathbf{1}\right) dU(\xi) \\ = \begin{cases} \frac{1}{2} \exp\left(|\kappa|^{1/2}\right) + \frac{1}{2} \exp\left(-|\kappa|^{1/2}\right) & \text{for } \mathscr{I}_{p} = S_{1}, \\ [\tilde{\pi}^{-1/2}\Gamma(p/2)/\Gamma((p-1)/2)] & \\ \times \int_{-1}^{1} \exp\left(|\kappa|^{1/2}u\right)(1-u^{2})^{(p-3)/2} du & \text{for } \mathscr{I}_{p} = S_{p} \text{ and } p \ge 2, \\ \exp\left(|\kappa|^{1/2} \operatorname{sgn}(\kappa)\right) & \text{for } \mathscr{I}_{p} = S_{1}^{+}, \end{cases}$$

for $\kappa \in R$, where $U(\cdot)$ denotes the uniform distribution on \mathscr{S}_p , $\operatorname{sgn}(\kappa)$ denotes the sign of κ , 1 denotes an arbitrary vector in \mathscr{S}_p , and $\Gamma(\cdot)$ denotes the gamma function. (The second equality for the case of $p \ge 2$ follows from Watson (1983, Appendix A, eqns. (1.1), (1.5), (1.6)).)

Of course, the approximate posterior probabilities of H_0 and H_1 , denoted $PP(H_0)$ and $PP(H_1)$, respectively, can be obtained from the approximate posterior odds statistics via

(2.5)
$$PP(H_0) = \frac{1}{1 + PO(M, \mu)}$$
 and $PP(H_1) = \frac{PO(M, \mu)}{1 + PO(M, \mu)}$

for $M = W_T$, LM_T , or LR_T .

 2 Bayesian tests also can be based on ratios of posterior expected losses (e.g., see Zellner (1971, pp. 295-6)). Such tests are more general than posterior odds tests. The application of the result of this paper to tests based on posterior expected losses is discussed briefly in Section 5 below.

Throughout, the prior Q_{μ} denotes a distribution function rather than a density. If Q_{μ} is a certain multivariate normal distribution with variance proportional to a scalar $\tau > 0$ (or the distribution of the absolute value of a normal variate for the one-sided testing case), then the posterior odds statistics $PO(W_T, \mu)$ etc. simplify. The distribution $\mu = \mu_{\tau}$ that corresponds to Q_{μ} in this case equals the square root of τ times a chi-square random variable with p degree of freedom (χ_p^2) , i.e., $\mu = \mu_{\tau} = \sqrt{\tau \chi_p^2}$. The statistic $PO(M, \mu)$ of (2.3) simplifies in this case to

(2.6)
$$PO(M, \mu_{\tau}) = \frac{1-\pi}{\pi} (1+\tau)^{-p/2} \exp\left[\frac{1}{2}\frac{\tau}{1+\tau}M\right]$$

in the two-sided testing case for $p \ge 1$ and to

(2.7)
$$PO(M, \mu_{\tau}) = \frac{1 - \pi}{\pi} (1 + \tau)^{-1/2} \times \exp\left[\frac{1}{2} \frac{\tau}{1 + \tau} M\right] 2\Phi\left(\left(\frac{\tau}{1 + \tau} |M|\right)^{1/2} \operatorname{sgn}(M)\right)$$

in the one-sided testing case, where $\Phi(\cdot)$ denotes the standard normal distribution function.³

Given the approximation of the posterior odds ratio by $PO(W_T, \mu)$, it is easy to see that there is a direct correspondence between a classical test and a posterior odds test. A classical Wald test rejects H_0 if $W_T > k_{p,\alpha}$. Here, $k_{p,\alpha}$ is the $(1 - \alpha)$ th quantile of a χ_p^2 distribution for two-sided tests with $p \ge 1$ and $k_{p,\alpha}$ is the $(1 - 2\alpha)$ th quantile of a χ_1^2 distribution for one-sided tests. An approximate posterior odds test rejects H_0 if $PO(W_T, \mu) > 1$. Since $PO(M, \mu)$ is a strictly increasing function of M (provided μ is not pointmass at 0), $PO(\cdot, \mu)$ has an inverse function $PO^{-1}(\cdot, \mu)$ and the approximate posterior odds test rejects if $W_T > PO^{-1}(1, \mu)$. Thus, the classical and approximate PO tests are equivalent whenever $PO^{-1}(1, \mu) = k_{p,\alpha}$ or, equivalently, whenever $PO(k_{p,\alpha}, \mu) = 1$. For fixed α and μ , one can always find π such that equality holds. Alternatively, for fixed μ and π , one can always find α such that equality holds. It is in this sense that the present paper demonstrates a correspondence between classical and Bayesian tests of H_0 versus H_1 .

3. THE PARAMETRIC MODEL

In this section, we define the parametric model, state high-level assumptions that are sufficient for our results, and define the W_T , LM_T , and LR_T statistics.

$$\frac{1-\pi}{\pi}\left(\frac{M}{p}\right)^{-p/2}\exp\left(\frac{1}{2}[M+p]\right).$$

³ It is sometimes of interest to a Bayesian from a robustness/sensitivity perspective to compute the maximum of the PO statistic over certain classes of priors, e.g., see Edwards, Lindman, and Savage (1963), Berger (1985, Sec. 4.3.3), and Berger and Sellke (1987). If one considers the class of multivariate normal priors referred to above, then for two-sided tests the maximum of the approximate PO statistic (2.6) over $\tau > 0$ is given by

Let Y_T denote the random data vector when the sample size is T for T = 1, 2.... Consider a parametric family $\{f_T(y_T, \theta): \theta \in \Theta\}$ of densities of Y_T with respect to some σ -finite measure γ_T , where $\Theta \subset \mathbb{R}^s$. The likelihood function is given by $f_T(\theta) = f_T(Y_T, \theta)$.

In many cases, the likelihood function $f_T(\theta)$ can be written as a product of two terms, one that depends on θ and another that does not. Often the latter term is the product over t = 1, ..., T of the conditional distribution of some weakly exogenous variables at time t given all of the preceding variables (exogenous or not). In such cases, these conditional distributions of the weakly exogenous variables need not be known in order for one to construct the classical or posterior odds test statistics considered here. The results below hold for any such distributions for which the assumptions on $f_T(\theta)$ hold. See Section 6 below for a more explicit discussion of the factoring of $f_T(\theta)$ into known and unknown terms.

Let $l_T(\theta) = \log f_T(\theta)$. Let $Dl_T(\theta)$ denote the *s* vector of partial derivatives of $l_T(\theta)$ with respect to θ . Let $D^2 l_T(\theta)$ denote the $s \times s$ matrix of second partial derivatives of $l_T(\theta)$ with respect to θ . We consider the standard case where the appropriate norming factors for $Dl_T(\theta)$ and $D^2 l_T(\theta)$ (so that each is $O_p(1)$ but not $o_p(1)$ as $T \to \infty$) are $T^{-1/2}$ and T^{-1} respectively.

Let $\theta_0 = (0', \delta'_0)'$ denote a value of θ in the null hypothesis. (Below we consider a pointmass prior distribution at θ_0 .) We say that a statement holds "under θ_0 " if it holds when the true density of Y_T is $f_T(\theta_0)$ for T = 1, 2, ...

The likelihood function/parametric model is assumed to satisfy the following assumptions.

Assumption 1: (a) θ_0 is an interior point of Θ .

(b) $f_T(\theta)$ is twice continuously partially differentiable in θ for all $\theta \in \Theta_0$ with probability one under θ_0 for all T large, where Θ_0 is some neighborhood of θ_0 .

(c) $-T^{-1}D^2l_T(\theta) \xrightarrow{p} \mathscr{I}(\theta)$ uniformly over $\theta \in \Theta_0$ under θ_0 for some nonrandom $s \times s$ matrix function $\mathscr{I}(\theta)$.

(d) $\mathscr{I}(\theta)$ is uniformly continuous on Θ_0 .

(e) $\mathscr{I} = \mathscr{I}(\theta_0)$ is positive definite.

Assumption 2: $T^{-1/2}Dl_T(\theta_0) \xrightarrow{d} Z \sim N(0, \mathscr{I})$ under θ_0 .

We comment briefly on Assumptions 1 and 2. Assumptions 1(a), (b), (d), and (e) are fairly common maximum likelihood (ML) regularity conditions. Differentiability in θ is assumed for simplicity at the expense of some generality. As is well known, it is not needed for standard ML estimation results and undoubtedly could be relaxed here with some increase in complexity.

Assumption 1(c) is a high-level assumption that requires a uniform weak law of large numbers (WLLN) to hold (since $-T^{-1}D^2l_T(\theta_0)$ can be written as a normalized sum of random variables by factoring the likelihood function using conditional distributions). The "uniformity" in Assumption 1(c) can be established, e.g., by using the generic uniform convergence results of Andrews (1992).

As stated, Assumption 1(c) allows one to be relatively agnostic regarding the temporal dependence and heterogeneity of the data. To verify 1(c), one needs to be more specific regarding these properties.

Assumption 2 is a second high-level assumption. It requires that the normalized score function satisfy a central limit theorem (CLT) (since $T^{-1/2}Dl_T(\theta_0)$ can be written as a normalized sum of random variables that are mean zero under weak additional conditions).

Let $\hat{\theta} (= \hat{\theta}_T)$ be the unrestricted ML estimator of θ . That is, $\hat{\theta}$ satisfies

(3.1)
$$l_T(\hat{\theta}) = \sup_{\theta \in \Theta} l_T(\theta) \quad \text{wp} \to 1 \text{ under } \theta_0.$$

Let $\tilde{\theta} (= \tilde{\theta}_T)$ be the *restricted* ML estimator of θ . That is, $\tilde{\theta}$ satisfies

(3.2)
$$\hat{\theta} \in \Theta = \{ \theta \in \Theta : \theta = (0', \delta')' \text{ for some } \delta \in \mathbb{R}^q \}$$
 and
 $l_T(\tilde{\theta}) = \sup_{\theta \in \tilde{\Theta}} l_T(\theta) \quad \text{wp} \to 1 \text{ under } \theta_0.$

We now introduce two additional high-level assumptions. We assume that the parametric model is sufficiently regular that the ML and restricted ML estimators are consistent under the null hypothesis.

Assumption 3:
$$\hat{\theta} \xrightarrow{p} \theta_0$$
 under θ_0 .
Assumption 4: $\tilde{\theta} \xrightarrow{p} \theta_0$ under θ_0 .

Primitive sufficient conditions for Assumptions 1-4 are given in Section 6 below.

We add a final comment concerning Assumption 1(a) for the case of one-sided tests. This assumption requires that the parametric model be defined for two-sided alternatives even though H_1 is one-sided. It implies that $\hat{\theta} = (\hat{\beta}', \hat{\delta}')$ is a two-sided unrestricted ML estimator. That is, $\hat{\beta}$ may take values greater than or less than zero. Assumption 1(a) can be restrictive in the one-sided case. For example, if β is a variance parameter, it requires that the likelihood function can be defined for $\beta < 0$, which is not always possible. On the other hand, it does cover many models of interest and it is an assumption that has been used frequently elsewhere in the literature. For example, it is imposed in the classic paper by Chernoff (1954) on large sample one-sided tests.

This completes the set of assumptions on the parametric model. We are now in a position to define the classical test statistics W_T , LM_T , and LR_T . For the case of two-sided tests with $p \ge 1$, define

(3.3)
$$W_{T} = (HT^{1/2}\hat{\theta})' [H\mathscr{I}_{T}^{-1}(\hat{\theta})H']^{-1}HT^{1/2}\hat{\theta},$$
$$LM_{T} = [T^{-1/2}Dl_{T}(\tilde{\theta})]'\mathscr{I}_{T}^{-1}(\tilde{\theta})T^{-1/2}Dl_{T}(\tilde{\theta}), \text{ and}$$
$$LR_{T} = -2(l_{T}(\tilde{\theta}) - l_{T}(\hat{\theta})), \text{ where}$$
$$H = [I_{p};0] \subseteq R^{p \times s} \text{ and } \mathscr{I}_{T}(\theta) = -T^{-1}D^{2}l_{T}(\theta).$$

Alternatively, one can define $\mathscr{I}_T(\theta)$ to be of outer product, rather than Hessian, form. Note that only the first *p* elements of $Dl_T(\tilde{\theta})$ are nonzero in the definition of LM_T , because $\partial l_T(\tilde{\theta})/\partial \delta = 0$ by the first order conditions for the restricted estimator $\tilde{\theta}$ (wp \rightarrow 1).

For the case of one-sided tests, let W_T^* , LM_T^* , and LR_T^* denote the expressions on the right-hand side of (3.3) and define the test statistics W_T , LM_T , and LR_T by

(3.4)
$$W_T = W_T^* \operatorname{sgn}(H\hat{\theta}), \quad LM_T = LM_T^* \operatorname{sgn}(H\mathscr{I}_T^{-1}(\tilde{\theta})Dl_T(\tilde{\theta})), \text{ and}$$

 $LR_T = LR_T^* \operatorname{sgn}(H\hat{\theta}).$

Note that a test based on W_T is equivalent in this case to the standard large sample t test, since W_T just equals the t statistic squared times its sign.

4. SPECIFICATION OF PRIORS

We take the prior probability of H_0 to be $\pi \in (0, 1)$ and that of H_1 to be $1 - \pi$. We are able to obtain approximations that hold for any parameter vector θ_0 in the null hypothesis and these approximations do not depend on θ_0 . In consequence, we take the prior over θ in H_0 to be given by pointmass at θ_0 , where θ_0 is an arbitrary parameter vector in H_0 . By doing so, we avoid placing a prior over the nuisance parameter vector δ . As is desirable, the results hold for any fixed value of the nuisance parameter.

Next we specify priors over θ in H_1 . We consider priors that depend on the sample size T. We do so in order to obtain large sample approximations that hold under the marginal distributions of the data both under H_0 and under H_1 and that capture relatively detailed effects of the chosen prior. We do not envisage one changing the prior as T changes in practice. Rather, in order to generate approximations for a fixed prior and fixed sample size, we find it useful theoretically to embed the prior in a sequence of priors that vary with T. The approach used here is analogous to the use of local alternatives in the analysis of the power of classical tests. If one does not change the prior with T, the large sample behavior of the posterior odds ratio in favor of H_1 is degenerate. It diverges to infinity under H_1 and converges to zero under H_0 . Using such fixed prior asymptotics, the effect of the prior is captured only crudely (see the discussion and references in Section 7).

For θ in H_1 , we write

$$(4.1) \qquad \theta = \theta_0 + T^{-1/2}h,$$

where θ_0 is as above and *h* is some R^s vector. We consider a prior Q_{μ} over vectors $h \in R^s$. Q_{μ} is fixed for all *T*. This corresponds to priors on θ that place greater mass on alternatives near θ_0 as *T* increases.

The prior Q_{μ} on h is defined as follows. Let V denote the linear subspace of R^{s} defined by

(4.2)
$$V = \{ \theta \in R^s : \theta = (0', \delta')' \text{ for some } \delta \in R^q \}.$$

The null hypotheses can be expressed as $H_0: \theta \in \tilde{\Theta} = \Theta \cap V$. We consider a prior Q_{μ} over h in \mathbb{R}^s that concentrates on the orthogonal complement of V with respect to the inner product $\langle h, l \rangle_{\mathscr{I}} = h' \mathscr{I} l$ for $h, l \in \mathbb{R}^s$, where \mathscr{I} is defined in Assumption 1. The orthogonal complement is denoted V^{\perp} . Since V is a q-dimensional subspace of \mathbb{R}^s , V^{\perp} is a p-dimensional subspace of \mathbb{R}^s . Let $\{a_1, \ldots, a_p\}$ be some basis of V^{\perp} and define $A = [a_1, \ldots, a_p] \in \mathbb{R}^{s \times p}$. For example, one can take

(4.3)
$$A = \begin{bmatrix} I_p \\ -\mathscr{I}_3^{-1}\mathscr{I}_2' \end{bmatrix}$$
, where $\mathscr{I} = \begin{bmatrix} \mathscr{I}_1 & \mathscr{I}_2 \\ \mathscr{I}_2' & \mathscr{I}_3 \end{bmatrix}$

for $\mathscr{I}_1 \in \mathbb{R}^{p \times p}$, $\mathscr{I}_2 \in \mathbb{R}^{p \times q}$, and $\mathscr{I}_3 \in \mathbb{R}^{q \times q}$. In consequence,

(4.4)
$$V^{\perp} = \{h \in \mathbb{R}^s : h = A\lambda \text{ for some } \lambda \in \mathbb{R}^p\}$$

The prior Q_{μ} that we consider concentrates on V^{\perp} and has contours given by certain ellipsoids. In other respects, the prior is arbitrary. Thus, the results given below apply for a wide range of priors. The ellipsoids over which Q_{μ} gives constant weight are the same as those considered by Wald (1943) in his demonstration of the property of asymptotically greatest weighted average power of classical Wald tests. The parameter vectors θ corresponding to different points on any such ellipsoid have the property that they are equally difficult to detect asymptotically—no direction away from the null is favored over any other.

The prior distributions are assumed to satisfy the following assumption.

Assumption 5: (a) The prior probabilities of H_0 and H_1 are $\pi \in (0,1)$ and $1 - \pi$ respectively.

(b) The prior distribution of θ under H_0 is pointmass at θ_0 , where θ_0 is the null parameter vector considered in Assumptions 1–4.

(c) The prior distribution of θ under H_1 is given by $\theta = \theta_0 + T^{-1/2}h$ and $h \sim Q_{\mu}$, where θ_0 is as in part (b). The distribution Q_{μ} of h is such that $h/||h||_{\mathscr{I}} \sim A(A'\mathscr{I}A)^{-1/2}\xi$, where ξ is a random vector that is uniformly distributed on the p-dimensional unit sphere \mathscr{I}_p , and $h/||h||_{\mathscr{I}}$ and $||h||_{\mathscr{I}}$ are independent.

Let μ denote the prior distribution of $||h||_{\mathscr{I}}$. Assumption 5 allows μ to be arbitrary (provided it is not pointmass at 0).

When p = 1 and H_1 is one-sided, the unit sphere \mathscr{I}_p referred to in Assumption 5(c) is a pointmass at 1. In this case, Assumption 5(c) places no restriction on the distribution of h other than that it lies in V^{\perp} . When p = 1and H_1 is two-sided, the unit sphere \mathscr{I}_1 equals $\{-1, 1\}$. In this case, Assumption 5(c) requires the prior on h to satisfy a symmetry property. If $\mathscr{I}_2 = 0$ (i.e., if the information matrix is diagonal between the parameters β and δ), the symmetry property just requires that h and -h be given equal prior density (or prior mass) for all h. When p > 1, the unit sphere \mathscr{I}_p is nondegenerate and Assumption 5(c) requires the prior Q_{μ} to have contours given by certain ellipsoids, as noted above.

For particular choices of distribution μ on $||h||_{\mathscr{I}}$, the distribution Q_{μ} and the approximation to the posterior odds ratio simplify. More specifically, suppose μ is the distribution of the square root of τ times a chi-square random variable with p degrees of freedom (i.e., $\mu \sim \sqrt{\tau \chi_p^2}$) for some $\tau > 0$. Then, in the two-sided testing case, h and θ have prior distributions given by

(4.5)
$$h \sim Q_{\mu} = N(0, \tau \Sigma)$$
 and $\theta \sim N(\theta_0, (\tau/T)\Sigma)$, where

$$\Sigma = A(A' \mathscr{I} A)^{-1} A'$$

$$= \begin{bmatrix} (\mathscr{I}_1 - \mathscr{I}_2 \mathscr{I}_3^{-1} \mathscr{I}_2')^{-1} & -(\mathscr{I}_1 - \mathscr{I}_2 \mathscr{I}_3^{-1} \mathscr{I}_2')^{-1} \mathscr{I}_2 \mathscr{I}_3^{-1} \\ -\mathscr{I}_3^{-1} \mathscr{I}_2' (\mathscr{I}_1 - \mathscr{I}_2 \mathscr{I}_3^{-1} \mathscr{I}_2')^{-1} & \mathscr{I}_3^{-1} \mathscr{I}_2' (\mathscr{I}_1 - \mathscr{I}_2 \mathscr{I}_3^{-1} \mathscr{I}_2')^{-1} \mathscr{I}_2 \mathscr{I}_3^{-1} \end{bmatrix}$$

and $N(0, \Sigma)$ denotes a multivariate normal distribution with mean 0 and covariance matrix Σ (which is singular when q > 0). With some algebraic manipulations, one can show that the upper left $p \times p$ block of Σ , $(A' \mathscr{I} A)^{-1}$, and $H \mathscr{I}^{-1} H'$ are equal. In consequence, the above prior on $\theta = (\beta', \delta')'$ corresponds to the following prior on β :

(4.6) $\beta \sim N(0, (\tau/T)H\mathscr{I}^{-1}H').$

Note that $(1/T)H\mathscr{I}^{-1}H'$ is the asymptotic variance of the unrestricted ML estimator $\hat{\beta}$.

In the one-sided testing case, the above prior $\mu \sim \sqrt{\tau \chi_1^2}$ on $||h||_{\mathscr{I}}$ yields priors on h, θ , and β given by

(4.7)
$$h \sim Q_{\mu} = |N(0, \tau \Sigma)|, \quad \theta \sim \theta_0 + |N(0, (\tau/T)\Sigma)|, \quad \text{and}$$

 $\beta \sim |N(0, (\tau/T)H\mathscr{I}^{-1}H')|$

for Σ as in (4.5), where $|N(0, \Sigma)|$ denotes the distribution of the absolute value of a random variable with $N(0, \Sigma)$ distribution.

For convenience, we refer to the above cases as Assumption 5^* :

Assumption 5^{*}: Assumption 5 holds with the distribution Q_{μ} of h given by $N(0, \tau \Sigma)$ for tests of two-sided alternatives and by $|N(0, \tau \Sigma)|$ for tests of one-sided alternatives, for some constant $\tau > 0$.

Under Assumption 5^* , the formula (2.3) for the approximate posterior odds ratio can be simplified.

LEMMA 1: Under Assumption 5^{*}, the expression for $PO(M, \mu)$ given in (2.3) simplifies to that given in (2.6) for two-sided tests and to that given in (2.7) for one-sided tests.

5. MAIN RESULTS

In this section, we state the main approximation results for the posterior odds statistic and discuss their interpretation.

5.1. Statement of the Main Results

To start, we define the posterior odds statistic $PO_T(Q_\mu)$ given the priors defined in Assumption 5:

(5.1)
$$PO_T(Q_\mu) = \frac{1-\pi}{\pi} \int f_T(\theta_0 + T^{-1/2}h) dQ_\mu(h) / f_T(\theta_0).$$

Note that for convenience we have defined $PO_T(Q_\mu)$ to be the posterior odds ratio in favor of H_1 , not in favor of H_0 . (The latter is just the reciprocal of $PO_T(Q_\mu)$.)

Below we say that probabilistic results hold "under H_0 " and "under H_1 " if they hold under the predictive densities of the data under H_0 and under H_1 respectively (i.e., under the marginal distribution of the data Y_T that is determined by the parametric model and the prior on θ under H_0 and under H_1 , as described in Assumption 5). Thus, "under H_0 " is equivalent to "under θ_0 ," whereas "under H_1 " depends on θ_0 and Q_{μ} .

The main result of the paper is the following:

THEOREM 1: Suppose Assumptions 1–5 hold. Then, under both H_0 and H_1 , we have: (a) $PO_T(Q_\mu) - PO(W_T, \mu) \xrightarrow{p} 0$, (b) $PO_T(Q_\mu) - PO(LM_T, \mu) \xrightarrow{p} 0$, and (c) $PO_T(Q_\mu) - PO(LR_T, \mu) \xrightarrow{p} 0$.

COMMENTS: 1. Theorem 1 holds not just for a single vector θ_0 , but for all null parameter vectors θ_0 for which Assumptions 1–5 hold, since $PO_T(W_T, \mu), \ldots, PO(LR_T, \mu)$ do not depend on θ_0 .

2. The result of Theorem 1 suggests approximating $PO_T(Q_\mu)$ by $PO(W_T, \mu)$, $PO(LM_T, \mu)$, or $PO(LR_T, \mu)$. At least in some cases, this approximation is quite good. For example, part (a) of Theorem 1 holds exactly (i.e., $PO_T(Q_\mu) = PO(W_T, \mu)$) in the case of a linear regression model with regression parameter θ , iid normal $(0, \sigma^2)$ errors, σ^2 known, and weakly exogenous regressors.⁴

3. Theorem 1 yields approximate sampling properties of posterior odds test statistics, because the asymptotic distribution of $PO(W_T, \mu)$ is easy to determine. For example, under θ_0 , it is given by $PO(Z^*, \mu)$ where Z^* has chi-squared distribution with p degrees of freedom (for two-sided tests).

5.2. Interpretation of Theorem 1

Theorem 1 shows that the posterior odds test, which rejects H_0 when $PO_T(Q_u) > 1$, is approximately equal to the test that rejects H_0 when

⁴ To see this, one can go through the proof of Theorem 1 in the Appendix and verify that all of the $o_p(1)$ terms are 0 in this case, provided one defines $\mathscr{I} = -T^{-1}D^2 l_T(\theta_0)$.

 $PO(W_T, \mu) > 1$, or equivalently, when

(5.2)
$$W_T > PO^{-1}(1,\mu),$$

where $PO^{-1}(\cdot, \mu)$ is the inverse function of the strictly increasing function $PO(\cdot, \mu)$. (The same holds with W_T replaced by LM_T or LR_T .) On the other hand, a classical Wald test of asymptotic significance level α rejects H_0 when

$$(5.3) \qquad W_T > k_{p,\alpha},$$

where $k_{p,\alpha}$ is as defined in Section 2. In consequence, the posterior odds test is approximately equal to a classical test, and vice versa, whenever α , μ , and π are such that

(5.4)
$$PO(k_{p,\alpha},\mu) = 1.$$

It can be shown that for any significance level $\alpha \in (0, 1)$ there exist pairs of priors (π, μ) such that (5.4) holds. In fact, there are many such (π, μ) pairs corresponding to a given α . Conversely, given any pair of priors (π, μ) , there exists a (unique) significance level α such that (5.4) holds. In fact, given any pair from the triplet (α, π, μ) , there exists a value of the third element such that (5.4) holds. Thus, for the special case of even prior odds $(\pi = 1/2)$, given any significance level α there exists a prior μ such that (5.4) holds and vice versa. These results imply that for any classical test there exist equivalent approximate posterior odds tests and vice versa. The mapping of posterior odds tests to classical tests is many-to-one.

The discussion above indicates that in large samples there are numerous posterior odds tests that are approximately equal. Different pairs of priors (π, μ) that yield the same value of $PO^{-1}(1, \mu)$ generate posterior odds tests that are approximately equal. This is a useful robustness property for posterior odds tests: The result of a posterior odds test holds not just for a single pair of priors (π, μ) , but for the whole family of priors that generate the same value of $PO^{-1}(1, \mu)$. Note that even if the prior probability π of H_0 is fixed, say at 1/2, there is still a whole family of priors μ that generate the same value of $PO^{-1}(1, \mu)$.

The p value of a test based on the statistic W_T , say, is a monotone decreasing function of W_T . In consequence, the approximate posterior odds ratio is a monotone decreasing function of the p value. In turn, the posterior probability of H_0 is a monotone increasing function of the p value. (It will not equal the p value in general.) More specifically, let P_{W_T} denote the p value of the test based on W_T . Then, by definition, $k_{p,P_{WT}} = W_T$. Hence, the approximate posterior odds statistic equals $PO(k_{p,P_{WT}}, \mu)$, which is a monotone decreasing function of P_{W_T} .

We now analyze the correspondence between classical and posterior odds tests more closely for two particular families of prior distributions μ on $||h||_{\mathscr{I}}$. The first family corresponds to priors $Q_{\mu} \sim N(0, \tau \Sigma)$ on h for different $\tau > 0$, or

p	.01	.05	$\frac{\alpha}{.10}$.25	.5ª
1 (one-sided)	881.	50.	14.	1.6	0.
1 (two-sided)	750.	41.	11.	.79	_
2	94.	16.	6.3	1.0	_
3	38.	9.5	4.5	.95	_
4	23.	6.9	3.6	.88	
5	16.	5.6	3.0	.81	_

TABLE I

Values of the Prior Parameter τ for Which Classical Tests of Significance Level α Are Equivalent to Approximate Posterior Odds Tests When $\pi = 1/2$

^a For α sufficiently large, there is no distribution μ of the form $\sqrt{\tau \chi_p^2}$ that solves (5.5) or (5.6). This accounts for the dashes in the table.

equivalently, to priors $\theta \sim N(\theta_0, (\tau/T)\Sigma)$. The prior distributions μ in this case equal $\sqrt{\tau \chi_p^2}$. Equation (5.4) holds for such priors if

(5.5)
$$(1+\tau)^{-p/2} \exp\left(\frac{1}{2}\frac{\tau}{1+\tau}k_{p,\alpha}\right) = \frac{\pi}{1-\pi}$$

for the case of two-sided tests with $p \ge 1$, and if

(5.6)
$$(1+\tau)^{-1/2} \exp\left(\frac{1}{2}\frac{\tau}{1+\tau}k_{1,\alpha}\right) 2\Phi\left(\left(\frac{\tau}{1+\tau}k_{1,\alpha}\right)^{1/2}\right) = \frac{\pi}{1-\pi}$$

for the case of one-sided tests.

Table I provides the values of τ that solve (5.5) and (5.6) when $\pi = 1/2$ for a variety of different values of α and p. The table shows that as α increases (so that the classical test rejects more frequently), the value of τ that yields an (approximately) equivalent posterior odds test decreases.

To illustrate the use of Table I, consider a situation where the upper-left $p \times p$ block of \mathscr{I}^{-1} equals I_p . Then, a posterior odds test with priors $\pi = 1/2$ and $\beta \sim N(0, 41/T)$, where T is the sample size, corresponds (approximately) to a two-sided classical test with significance level $\alpha = .05$. A posterior odds test with $\pi = 1/2$ and $\beta \sim |Z_T|$ for $Z_T \sim N(0, 50/T)$ corresponds to a one sided classical test with significance level $\alpha = .05$.

Next, we consider the family of prior distributions μ on $||h||_{\mathscr{F}}$ that equal pointmass at r_* for different $r_* > 0$. Such distributions correspond to the prior on θ being given by the distribution of $\theta_0 + T^{-1/2}A(A'\mathscr{I}A)^{-1}\xi r_*$ and the prior on β being given by the distribution of $T^{-1/2}(H\mathscr{I}^{-1}H')^{-1/2}\xi r_*$, where ξ is uniformly distributed on \mathscr{I}_p . (Note that the variance of β under this prior is $(r_*^2/T)H\mathscr{I}^{-1}H'$, which equals r_*^2 times the asymptotic variance of the ML estimator $\hat{\beta}$.) Equation (5.4) holds for such priors if

(5.7)
$$\exp\left(-r_{*}^{2}/2\right)g_{p}\left(k_{p,\alpha}r_{*}^{2}\right) = \frac{\pi}{1-\pi}.$$

In particular, for the case of one-sided tests, this reduces to

(5.8)
$$\exp\left(-r_{*}^{2}/2 + \sqrt{k_{1,\alpha}}r_{*}\right) = \frac{\pi}{1-\pi}.$$

Equation (5.8) can be solved analytically to yield $r_* = (k_{1,\alpha})^{1/2} \pm (k_{1,\alpha} - 2\log(\pi/(1-\pi)))^{1/2}$ provided $r_* > 0$. Thus, for one-sided tests with $\pi = 1/2$, we have $r_* = 2\sqrt{k_{1,\alpha}}$. Here, $\sqrt{k_{1,\alpha}}$ equals the critical value for the Wald t statistic. Thus, one needs the prior on β to put pointmass at twice the critical value for the t statistic times $\sigma_{\beta} = (H\mathscr{I}^{-1}H/T)^{1/2}$ in order for the posterior odds test and significance level α tests to be equivalent (approximately), where σ_{β} is the asymptotic standard error of the ML estimator $\hat{\beta}$. In particular, for $\alpha = .01, .05, .10, \text{ and } .25, \text{ one has } r_*$ equal to σ_{β} times 4.65, 3.29, 2.56, and 1.35, respectively.

5.3. Bayesian Versus Classical Tests That Are Impartial Between the Null and a Given Alternative

Suppose one wants a test that treats the null and a particular alternative distribution impartially. A Bayesian test can be constructed in this case by specifying a pointmass prior distribution at the alternative distribution of interest under H_1 and by taking the prior probability of H_1 to equal that of H_0 , i.e., $\pi = 1/2$. In contrast, a classical test can be constructed that has the property that its probability of type I error (significance level) equals its probability of type II error for the alternative distribution of interest.

How do these Bayesian and classical tests compare? Using the results above and those of Andrews (1989), we find that for one-sided alternatives the two tests are asymptotically equivalent and for two-sided tests they are not asymptotically equivalent, but are quite close.

First, consider one-sided alternatives. Suppose the alternative distribution of interest has β equal to β_* . Then, for a Bayesian posterior odds test, a pointmass prior distribution on β_* under H_1 corresponds to the distribution μ introduced above being pointmass at $r_* = \beta_* / \sigma_\beta$, where $\sigma_\beta = (H \mathscr{I}^{-1} H' / T)^{1/2}$. For this prior, the (approximate) posterior odds test rejects H_0 if $W_T > k_{1,\alpha}^*$, where $k_{1,\alpha}^*$ solves (5.8) with $\pi = 1/2$, i.e., $k_{1,\alpha}^* = (r_*/2)^2 = \beta_*^2 / (4\sigma_\beta^2)$.

On the other hand, asymptotic inverse power results in Andrews (1989) give the (approximate) magnitude of β for which the probability of type II error of a Wald, LM, or LR test of level α equals α . The magnitude is $2z_{\alpha}\sigma_{\beta}$, where z_{α} is the $(1 - \alpha)$ th quantile of the standard normal distribution. In consequence, for a test to have significance level equal to the probability of type II error against $\beta = \beta^*$, one needs α to satisfy $\beta_* = 2z_{\alpha}\sigma_{\beta}$ or $z_{\alpha} = \beta_*/(2\sigma_{\beta})$. A Wald t test rejects if the t statistic exceeds $z_{\alpha} = \beta_*/(2\sigma_{\beta})$, or equivalently, if W_T (which equals the squared t statistic times the sign of the t statistic) exceeds $\beta^2_*/(4\sigma^2_{\beta})$. Thus, the impartial posterior odds and classical tests are equivalent asymptotically.

Next, for two-sided tests, similar calculations can be made, but one does not find that the impartial posterior odds and classical tests are exactly equivalent asymptotically. Nevertheless, they do not differ greatly. For example, suppose p=1 and β_* and σ_{β} are such that $\beta_*/\sigma_{\beta} = 3.605$. Then, by Table I of Andrews (1989), the classical test with size equal to one minus power at β_* has $\alpha = .05$. This asymptotic test rejects if $W_T > 3.84$, using the χ_1^2 table. For the impartial posterior odds test, on the other hand, $r_* = \beta_* / \sigma_{\beta} = 3.605$ corresponds to a critical value $k_{1,\alpha} = 3.98$, according to equation (5.7). That is, the approximate posterior odds test rejects if W_T (or LM_T or LR_T) exceeds 3.98. Since the critical values 3.98 and 3.84 are quite close, the posterior odds and classical tests are quite close asymptotically. If β_* and σ_{β} are such that $r_* = \beta_* / \sigma_{\beta} = 4.902$ (or 2.926), then the impartial classical test must have α equal to .01 (.10 respectively) and the asymptotic critical values of the impartial posterior odds and classical tests are 6.72 and 6.63 (2.89 and 2.71 respectively). In each case, the impartial posterior odds and classical tests are quite close asymptotically.

We now add several caveats to the results described in this subsection. First, the results are established only for standard asymptotic scenarios, where the ML estimator is asymptotically normal. They also should apply if the asymptotic distribution of the ML estimator is a location shift family of symmetric distributions, such as mixed normal distributions. On the other hand, they cannot be expected to hold for tests involving unit root parameters in models with stochastic trends. Second, the results depend on the difference between the prior on the nuisance parameter δ under H_0 and its prior under H_1 going to zero as $T \to \infty$. If one had different priors on δ asymptotically under the two hypotheses, then the results would not hold. (In finite samples, this cause of a difference between impartial Bayesian and classical tests can be illustrated by considering tests of H_0 : $Y \sim N(0, \sigma_1^2)$ versus H_1 : $Y \sim N(\beta, \sigma_2^2)$ where $\sigma_1^2 \neq \sigma_2^2$.) Third, for two-sided tests, the results depend on the restrictions on the prior on β under H_1 (as specified in Assumption 5(c)).

5.4. Tests Based on Expected Posterior Losses

In this section, we show that the results above, which show a correspondence between Bayesian posterior odds tests and classical tests, also provide a correspondence between Bayesian posterior expected loss tests and classical tests.

Let $L(\theta, H_0)$ (resp., $L(\theta, H_1)$) denote the loss when θ is the true parameter and H_0 (resp. H_1) is chosen. By assumption, $L(\theta, H_j) \ge 0$ and $L(\theta, H_j) = 0 \forall \theta$ in H_j for j = 0, 1. A Bayesian posterior expected loss test rejects H_0 (i.e., chooses H_1) if the posterior expected loss of H_1 is less than that of H_0 , or equivalently, if the ratio of the posterior expected loss of H_0 over that of H_1 , denoted $REPL_T$, is greater than 1. A Bayesian posterior odds test is a special case for which $L(\theta, H_1) = L(\theta', H_0) \forall \theta$ in H_0 and $\forall \theta'$ in H_1 .

Let $L(\theta_0, H_1) = 1$ without loss of generality. Suppose one takes $L(\theta, H_0)$ and the prior on θ under H_1 to be such that their product equals the prior on θ

under H_1 specified in Assumption 5 above. Then, under the other assumptions above, $REPL_T - PO(W_T, \mu) \xrightarrow{p} 0$ under H_0 and under H_1 , and likewise for LM_T and LR_T , where $PO(W_T, \mu)$ is as defined in (2.3) except with $(1 - \pi)/\pi$ replaced by $\int L(\theta_0 + T^{-1/2}h, H_0) dQ_{\mu}(h)(1 - \pi)/\pi$. This result gives a direct correspondence between classical tests and certain posterior expected loss tests.⁵

6. NONLINEAR MODELS

In this section, we consider nonlinear dynamic models. We provide primitive assumptions that are sufficient for Assumptions 1-4 of Section 3. For simplicity, we consider strictly stationary *m*th order Markov models.

The sample of observations is given by

(6.1)
$$Y_T = \{(S_t, X_t) : t \leq T\},\$$

where $\{S_t: t \leq T\}$ are endogenous variables and $\{X_t: t \leq T\}$ are weakly exogenous variables.⁶ Let

(6.2)
$$\{g_t(\theta): \theta \in \Theta\} = \{g_t(S_t|S_1, \dots, S_{t-1}; X_1, \dots, X_t): \theta \in \Theta\}$$

denote a parametric family of conditional densities (with respect to some measure λ) of S_t given $S_1, \ldots, S_{t-1}, X_1, \ldots, X_t$ evaluated at the random variables $S_1, \ldots, S_t, X_1, \ldots, X_t$, where $\Theta \subset \mathbb{R}^s$. Let

(6.3)
$$h_t = h_t(X_t|S_1, \dots, S_{t-1}; X_1, \dots, X_{t-1})$$

denote the conditional density (with respect to some measure) of X_t given $S_1, \ldots, S_{t-1}, X_1, \ldots, X_{t-1}$ evaluated at the random variables $S_1, \ldots, S_{t-1}, X_1, \ldots, X_t$. By the assumption of weak exogeneity, h_t does not depend on θ .

The likelihood function $f_T(\theta)$ and log likelihood function $l_T(\theta)$ are given by

(6.4)
$$f_T(\theta) = \prod_{t=1}^T g_t(\theta) \cdot \prod_{t=1}^T h_t \text{ and } l_T(\theta) = \sum_{t=1}^T \log g_t(\theta) + \sum_{t=1}^T \log h_t,$$

where \sum_{1}^{T} denotes $\sum_{t=1}^{T}$.

We consider the case where $\{(S_t, X_t): t \ge 1\}$ is part of a doubly infinite strictly stationary ergodic sequence $\{(S_t, X_t): t = ..., 0, 1, ...\}$ and $\{S_t: t = ..., 0, 1, ...\}$ is *m*th order Markov for some integer $m \ge 0$. In this case, the function $\mathscr{I}(\theta)$

⁵ The proof of this result holds by the same argument as used to establish Theorem 1 with the prior on θ under H_1 replaced by the product of $L(\theta, H_1)$ and the prior on θ under H_1 divided by its integral over θ in H_1 (i.e., by $\int L(\theta_0 + T^{-1/2}h) dQ_{\mu}(h)$) in order to ensure that the product integrates to one, and hence, is a proper distribution.

⁶ Weak exogeneity of $\{X_t: t \in T\}$, defined in Engle, Hendry, and Richard (1983), implies that the likelihood function for Y_T can be factored into two pieces, one of which contains conditional distributions of S_t and depends on θ and the other of which contains conditional distributions of X_t and does not depend on θ ; see below.

equals $-E\partial^2 \log g_t(\theta)/\partial\theta\partial\theta'$. By definition, $\{S_t: t = ..., 0, 1, ...\}$ is mth order Markov if the conditional distribution of S_t given $\mathscr{F}_{t-1} = \sigma(..., S_{t-2}, S_{t-1};$ $..., X_{t-1}, X_t)$ equals the conditional distribution of S_t given $S_{t,m} = (S_{t-m}, ..., S_{t-1})$ and $X_{t,m} = (X_{t-m}, ..., X_t)$ for all t. The Markov assumption yields the simplification that the summands $\log g_t(\theta)$ in the log-likelihood function are strictly stationary and ergodic for t > m. Without the Markov assumption this would not be the case, because the number of relevant observed variables in the conditioning set would vary with t.

The following assumption provides primitive sufficient conditions for Assumptions 1–4 of Section 3:

Assumption NL: (a) Θ is compact and θ_0 lies in the interior of Θ .

(b) $\{(S_t, X_t): t = ..., 0, 1, ...\}$ is strictly stationary and ergodic and $\{S_t: t = ..., 0, 1, ...\}$ is mth order Markov under θ for each $\theta \in \Theta$.

(c) $g_t(\theta)$ is continuous in θ on Θ and twice continuously partially differentiable in θ on Θ_0 with probability one under θ_0 , where Θ_0 is some compact set that contains a neighborhood of θ_0 .

(d) $g_t(\theta) \neq g_t(\theta_0)$ with positive probability under $\theta_0 \ \forall \theta \in \Theta$ with $\theta \neq \theta_0$.

(e) $E \sup_{\theta \in \Theta} |\log g_t(\theta)| < \infty$, $E \sup_{\theta \in \Theta_0} ||\partial \log g_t(\theta) / \partial \theta|| < \infty$,

$$E \|\partial \log g_t(\theta_0) / \partial \theta\|^2 < \infty, \quad and \quad E \sup_{\theta \in \Theta_0} \|\partial^2 \log g_t(\theta) / \partial \theta \partial \theta'\| < \infty.$$

(f) $\mathscr{I} = -E\partial^2 \log g_t(\theta_0)/\partial\theta\partial\theta'$ is positive definite.

The expectations in parts (e) and (f) are taken under θ_0 .

Assumption NL constitutes a fairly standard set of ML regularity conditions for stationary and ergodic situations.

LEMMA 2: Assumption NL implies Assumptions 1–4.

Thus, Assumptions NL and 5 are sufficient for the result of Theorem 1 to hold.

7. RELATED RESULTS IN THE LITERATURE

Here we discuss some asymptotic results for posterior odds tests due to Jeffreys (1961, pp. 246–247, 249–250), Lindley (1961), Schwarz (1978), Kass and Vaidyanathan (1992), and Phillips (1992). In particular, we focus on the relationship between these results and the results presented above.

Kass and Vaidyanathan (1992, eqn. (2.3)) (hereafter denoted KV) provide a family of approximations to the PO statistic that depend on the choice of certain functions b_0 and b. Their approximations do not yield the approximate

PO statistic to be a monotone function of W_T , LM_T , or LR_T . Their approximations are closest to being such a function, however, if one takes b_0 and b to equal the priors on the parameters under H_0 and under H_1 respectively.

In this case, their approximate PO statistic in favor of H_1 is given by

(7.1)
$$\frac{1-\pi}{\pi}\frac{\pi_1(\hat{\theta})}{\pi_0(\tilde{\delta})}(2\tilde{\pi})^{p/2}\frac{\det\left(T\left[\mathscr{I}_T(\tilde{\theta})\right]_{22}\right)^{1/2}}{\det\left(T\mathscr{I}_T(\hat{\theta})\right)^{1/2}}\exp\left(\frac{1}{2}LR_T\right),$$

where $\pi_1(\cdot)$ is the prior on θ under $H_1, \pi_0(\cdot)$ is the prior on δ under $H_0, \pi, \hat{\theta}$, and $\tilde{\theta}$ are as above, $[\mathscr{I}_T(\tilde{\theta})]_{22}$ is the lower right $q \times q$ submatrix of $\mathscr{I}_T(\tilde{\theta})$, and det(A) denotes the determinant of the matrix A. This formula reduces to that given by Lindley (1961) for the case where p = 1. It is similar to, but different from, the approximation given by Jeffreys (1961) for the case p = 1.

KV show that the approximation (7.1) is valid to within a multiplicative error of O(1/T) (i.e., the ratio of exact to approximate PO equals 1 + O(1/T)) with probability one under H_0 and under H_1 using asymptotics that employ the same prior for all T.

A direct comparison of KV's approximations to those given in this paper is not straightforward, because different asymptotics are employed. Under KV's asymptotics, the PO statistic has limit zero or infinity depending on whether H_0 or H_1 is true. In consequence, multiplicative approximation errors are considered and the prior only affects the approximation in a relatively crude fashion. With the asymptotics used in this paper, the PO statistic has a nondegenerate limit as $T \rightarrow \infty$, so additive approximation errors are considered and the whole prior affects the approximation.

KV's multiplicative approximation errors are O(1/T), which is of second order and is quite desirable. This does not necessarily translate into additive approximation errors of o(1) under H_1 , however, because the true PO statistic diverges to infinity very quickly under H_1 using their asymptotics. On the other hand, the additive approximation errors of the approximations given in this paper are necessarily $o_p(1)$ under H_0 and under H_1 using our asymptotics, but the corresponding multiplicative approximation errors are not $O_p(1/T)$ in general. It seems likely that the approximations given here are more accurate than KV's in some cases and less accurate in others. The former is known to be true, since the approximations given here are exact for linear regression models with iid normal errors and known variance for a wide variety of priors, whereas KV's approximations are not exact in these cases.

Next, we consider Schwarz's (1978) asymptotic results for Bayesian model selection procedures. His results yield the following approximation to the PO statistic in favor of H_1 :

(7.2)
$$T^{-p/2} \exp\left(\frac{1}{2}LR_T\right).$$

The same formula applies for all prior probabilities $\pi \in (0,1)$ of H_0 , for all (proper) priors over the values of θ in H_0 , and for all priors over those values of

 θ in H_1 . Obviously, his approximation can be quite crude given its extremely broad range of applicability. (One can make the PO statistic take any value in $(0, \infty)$ by suitable choice of π . Thus, it is clear that Schwarz's approximation does not hold uniformly in π and can have arbitrarily poor accuracy.) This crudeness of approximation is both a virtue and a drawback. It is a virtue, if one wants to construct an asymptotic procedure that is independent of the prior, as does Schwarz. It is a drawback, however, if one wants a reasonably accurate approximation of the PO statistic, as is desired here.

Schwarz's results apply to a subclass of the models considered in this paper, viz., iid linear exponential models. On the other hand, his results apply to a broader class of hypotheses. In addition to considering hypotheses of the form H_0 : $\beta = 0$ versus H_1 : $\beta \neq 0$, which correspond to choosing between nested models of different dimensions, he also considers choosing between nonnested iid linear exponential models. The type of asymptotics considered by Schwarz differs from that considered here. He fixes the values of the (normalized) sufficient statistics of the linear exponential model for all T. Thus, in his asymptotics, nothing is random.

Schwarz's approximations are valid in the sense that the ratio of the true PO statistic to the approximate posterior odds statistic (6.2) is bounded away from zero and infinity for all T. Obviously, this is a very weak approximation result. For the purposes of obtaining reasonably accurate approximations, one would like the ratio to have limit one as $T \rightarrow \infty$, as with KV's approximations.

Last, we discuss some results of Phillips (1992, Remark 3.2(ii)). Phillips' results are similar to those given here in that they establish an asymptotic correspondence between Bayesian posterior odds and classical tests. His results differ, however, in terms of the priors considered, the models considered, and the choice of distributions under which the asymptotics hold. Thus, his results and those given here are more complements than substitutes.

More specifically, Phillips' results and ours differ as follows: (i) Phillips discusses the asymptotic correspondence when the asymptotics are derived under the null, whereas we consider the asymptotic correspondence under the null and also under the alternative, (ii) Phillips considers a noninformative (improper) prior, whereas we consider classes of proper priors, and (iii) Phillips considers linear vector autoregressive models that are stationary under the null and possibly nonstationary under the alternative, whereas we consider nonlinear models with random variables that are nontrending under the null and the alternative.⁷

Cowles Foundation for Research in Economics, Dept. of Economics, Yale University, P.O. Box 208281 Yale Station, New Haven, CT 06520-8281, U.S.A.

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⁷ Note that Phillips (1992) considers general nonstationary linear models in most of his paper, but the section dealing with an asymptotic correspondence between Bayesian and classical tests considers a null hypothesis under which the random variables are stationary.

APPENDIX

Without loss of generality, we set the prior probability π of H_0 to be 1/2 throughout the Appendix. This simplifies notation, since the multiplicative factor $(1 - \pi)/\pi$ reduces to 1. The proofs of Lemmas 1 and 2 follow those of Theorem 1. We start by stating an assumption, several definitions, and four lemmas that are used in the proof of Theorem 1.

Assumption 1': $T^{-1/2}Dl_T(\theta_0) = O_p(1)$ under θ_0 .

Assumption 1' is implied by Assumption 2. Assumption 1' is introduced, so that it is evident below where the full strength of Assumption 2 is used in the proofs.

Define

(A.1)
$$\overline{\theta} = \mathscr{I}^{-1} T^{-1/2} Dl_T(\theta_0).$$

LEMMA A-1: Suppose Assumptions 1, 1', and 3 hold. Then, $T^{1/2}(\hat{\theta} - \theta_0) - \bar{\theta} \xrightarrow{p} 0$ under θ_0 .

Next, we define an unobserved large sample approximation to the posterior-odds statistic $PO_T(Q_\mu)$. Let

(A.2)
$$\overline{PO}_T(Q_{\mu}) = \int \exp\left[-\frac{1}{2}(\bar{\theta}-h)'\mathscr{I}(\bar{\theta}-h)\right] dQ_{\mu}(h) / \exp\left[-\frac{1}{2}\bar{\theta}'\mathscr{I}\bar{\theta}\right].$$

LEMMA A-2: Suppose Assumptions 1, 1', and 3 hold. Then, $PO_T(Q_\mu) - \overline{PO}_T(Q_\mu) \xrightarrow{p} 0$ under θ_0 .

For the case of two-sided tests, we define an *approximate Wald* statistic \overline{W}_T by

(A.3)
$$\overline{W}_T = (H\overline{\theta})' (H\mathscr{I}^{-1}H')^{-1} H\overline{\theta}.$$

For the case of one-sided tests, we let \overline{W}_T^* equal the right-hand side of (A.3) and we define \overline{W}_T to equal \overline{W}_T^* sgn ($H\overline{\theta}$).

The approximate posterior-odds statistic $\overline{PO}_T(Q_\mu)$ simplifies to a simple function of the approximate Wald statistic:

LEMMA A-3: Suppose Assumption 5 holds. Then, $\overline{PO}_T(Q_\mu) = PO(\overline{W}_T, \mu)$.

Combining Lemmas A-2 and A-3, one sees that the results of Theorem 1 under θ_0 are equivalent to

(A.4)
$$PO(\overline{W}_T, \mu) - PO(W_T, \mu) \xrightarrow{\nu} 0$$
 under θ_0

and likewise with W_T replaced by LM_T and LR_T . The latter results are relatively straightforward to establish under Assumptions 1–5 (see below).

To obtain the results of Theorem 1 under H_1 , it suffices to show that they hold under θ_0 and that the alternative marginal densities $\{\int f_T(\theta_0 + T^{-1/2}h) dQ_\mu(h): T \ge 1\}$ of the data vectors $\{Y_T: T \ge 1\}$, under the parametric model $\{f_T(\theta): \theta \in \Theta\}$ and the prior Q_μ , are contiguous to the null densities $\{f_T(\theta_0): T \ge 1\}$ of $\{Y_T: T \ge 1\}$.

LEMMA A-4: Suppose Assumptions 1–5 hold. Then, the alternative marginal densities $\{f_T(\theta_0 + T^{-1/2}h) dQ_\mu(h): T \ge 1\}$ of the data vectors $\{Y_T: T \ge 1\}$ are contiguous to the null densities $\{f_T(\theta_0): T \ge 1\}$.

PROOF OF LEMMA A-1: Lemma A-1 is established by taking a mean value expansion about θ_0 of each of the elements of $Dl_T(\hat{\theta})$. Details can be found in the proof of Lemma 1 of Andrews and Ploberger (1994). Q.E.D.

PROOF OF LEMMA A-2: All probability calculations in this proof are made "under θ_0 ." For $0 < M < \infty$, define

(A.5)
$$PO_{TM} = \int_{\|h\| \le M} f_T(\theta_0 + T^{-1/2}h) \, dQ_\mu(h) / f_T(\theta_0)$$
 and

(A.6)
$$\overline{PO}_{TM} = \int_{\|h\| \leq M} \exp\left(-\frac{1}{2}(\overline{\theta} - h)'\mathscr{I}(\overline{\theta} - h)\right) dQ_{\mu}(h) / \exp\left(-\frac{1}{2}\overline{\theta}'\mathscr{I}\overline{\theta}\right).$$

For any $\varepsilon > 0$,

(A.7)
$$P(|PO_{T}(Q_{\mu}) - \overline{PO}_{T}(Q_{\mu})| > \varepsilon)$$
$$\leq P(|PO_{T}(Q_{\mu}) - PO_{TM}| > \varepsilon) + P(|PO_{TM} - \overline{PO}_{TM}| > \varepsilon)$$
$$+ P(|\overline{PO}_{T}(Q_{\mu}) - \overline{PO}_{TM}| > \varepsilon).$$

Hence, it suffices to show that (1) given any $\eta > 0$ we can choose $T^* < \infty$ and $M < \infty$ sufficiently large so that $P(|PO_T(Q_\mu) - PO_{TM}| > \varepsilon) < \eta$ and $P(|\overline{PO}_T(Q_\mu) - \overline{PO}_{TM}| > \varepsilon) < \eta$ for all $T \ge T^*$ and (2) $PO_{TM} - \overline{PO}_{TM} \xrightarrow{p} 0 \ \forall 0 < M < \infty$. We show (1) first. We have

(A.8)
$$P(|PO_T(Q_{\mu}) - PO_{TM}| > \varepsilon)$$

$$\leq \varepsilon^{-1}E|PO_T(Q_{\mu}) - PO_{TM}|$$

$$= \varepsilon^{-1}E\int_{||h|| > M} [f_T(\theta_0 + T^{-1/2}h)/f_T(\theta_0)] dQ_{\mu}(h)$$

$$= \varepsilon^{-1}\int_{||h|| > M} dQ_{\mu}(h),$$

where the second equality holds by Fubini's Theorem and the fact that $E[f_T(\theta_0 + T^{-1/2}h)/f_T(\theta_0)] = 1 \forall h$. The right-hand side (rhs) of (A.8) can be made arbitrarily small for all T by taking M large.

Next, we have

(A.9)
$$\begin{aligned} \left| \overline{PO}_{T}(Q_{\mu}) - \overline{PO}_{TM} \right| &= \exp\left[\frac{1}{2} \overline{\theta}' \mathscr{I} \overline{\theta} \right] \int_{\|h\| > M} \exp\left[-\frac{1}{2} (\overline{\theta} - h)' \mathscr{I} (\overline{\theta} - h) \right] dQ_{\mu}(h) \\ &\leq \exp\left[\frac{1}{2} \left\| T^{-1/2} Dl_{T}(\theta_{0}) \right\|^{2} \cdot \left\| \mathscr{I}^{-1} \right\| \right] \int_{\|h\| > M} dQ_{\mu}(h), \end{aligned}$$

where the inequality uses Assumption 1(e). The first term on the rhs of (A.9) is $O_p(1)$ by Assumptions 1(e) and 1' and the second term on the rhs can be made arbitrarily small by taking M large.

We now establish (2). A two term Taylor series expansion gives

(A.10)
$$l_T(\theta_0 + T^{-1/2}h) - l_T(\theta_0) = h'T^{-1/2}Dl_T(\theta_0) + \frac{1}{2}h'T^{-1}D^2l_T(\theta_0)h + r_{1T}(h),$$

where the remainder term $r_{1T}(h)$ satisfies

(A.11)
$$\sup_{|h| \leq M} \|r_{1T}(H)\| \leq M^{2} \sup_{\theta \colon \|T^{1/2}(\theta - \theta_{0})\| \leq M} \|T^{-1}D^{2}l_{T}(\theta) - T^{-1}D^{2}l_{T}(\theta_{0})\|$$

$$\leq M^{2} \sup_{\theta \in \Theta_{0}} \|T^{-1}D^{2}l_{T}(\theta) - \mathscr{I}(\theta)\|$$

$$+ M^{2} \sup_{\theta \colon \|T^{1/2}(\theta - \theta_{0})\| \leq M} \|\mathscr{I}(\theta) - \mathscr{I}(\theta_{0})\|$$

$$+ M^{2} \|T^{-1}D^{2}l_{T}(\theta_{0}) + \mathscr{I}(\theta_{0})\|$$

$$= o_{p}(1),$$

where the equality uses Assumptions 1(c) and (d). In addition,

(A.12)
$$h'T^{-1}D^2l_T(\theta_0)h = -h'\mathscr{I}h + r_{2T}(h), \text{ where } \sup_{h: \|h\| \le M} |r_{2T}(h)| = o_p(1),$$

by Assumption 1(c). It follows from (A.11) and (A.12) that

(A.13)
$$\exp[r_{1T}(h) + r_{2T}(h)] = 1 + s_T(h)$$
, where $\sup_{h: \|h\| \le M} |s_T(h)| = o_p(1)$.

Combining (A.10) and (A.12) and using the definition of $\overline{\theta}$ yields

(A.14)
$$l_{T}(\theta_{0} + T^{-1/2}h) - l_{T}(\theta_{0}) = h' \mathscr{I} \overline{\theta} - \frac{1}{2}h' \mathscr{I} h + r_{1T}(h) + r_{2T}(h)$$
$$= \frac{1}{2} \overline{\theta}' \mathscr{I} \theta \overline{\theta} - \frac{1}{2} (\overline{\theta} - h)' \mathscr{I} (\overline{\theta} - h) + r_{1T}(h) + r_{2T}(h).$$

Combining (A.5), (A.6), (A.13), and (A.14) gives

(A.15)
$$PO_{TM} = \int_{\|h\| \leqslant M} \exp\left[l_T\left(\theta_0 + T^{-1/2}h\right) - l_T(\theta_0)\right] dQ_\mu(h)$$
$$= \int_{\|h\| \leqslant M} \exp\left[\frac{1}{2}\overline{\theta}' \mathscr{I}\overline{\theta} - \frac{1}{2}(\overline{\theta} - h)' \mathscr{I}(\overline{\theta} - h)\right] (1 + s_T(h)) dQ_\mu(h)$$
$$= \overline{PO}_{TM} + o_p(1),$$

where the third equality uses $\overline{PO}_{TM} = O_p(1)$, which follows from a close analogue to (A.9). This completes the proof. O.E.D.

PROOF OF LEMMA A-3: Let P and P^{\perp} denote the projection matrices onto V and V^{\perp} respectively, with respect to $\langle \cdot, \cdot \rangle_{\mathscr{I}}$. The projection matrix P^{\perp} is given by $P^{\perp} = AH$, where A and Here as in the text. To see this, note that P^{\perp} is characterized by (i) $P^{\perp}v = 0 \quad \forall v \in V$ and (ii) $P^{\perp}m = m \quad \forall m \in V^{\perp}$. Condition (i) holds for $P^{\perp} = AH$ by simple algebra. Condition (ii) holds for $P^{\perp} = AH$ because for $m = (m'_1, m'_2)' \in V^{\perp}$, $v' \not = m = 0 \quad \forall v \in V$ iff $[0:I_q] \not = m = 0$ iff $m = Am_1$. In consequence, $AHm = AHAm_1 = Am_1 = m \quad \forall m \in V^{\perp}$ (using the fact that $HA = I_p$).

Now, twice the exponent of the integrand of $\overline{PO}_T(Q_\mu)$ can be rewritten as follows:

(A.16)
$$\overline{\theta}' \mathscr{I} \overline{\theta} - (h - \overline{\theta})' \mathscr{I} (h - \overline{\theta}) = -h' \mathscr{I} h + 2h' \mathscr{I} \overline{\theta} = -h' \mathscr{I} h + 2h' \mathscr{I} P^{\perp} \overline{\theta}$$
$$= (P^{\perp} \overline{\theta})' \mathscr{I} P^{\perp} \overline{\theta} - (h - P^{\perp} \overline{\theta})' \mathscr{I} (h - P^{\perp} \overline{\theta}),$$

where the second equality holds because $h \in V^{\perp}$ implies $h' \mathscr{I} P \overline{\theta} = 0$. Define $Z = (A' \mathscr{I} A)^{1/2} H \overline{\theta}$. Let ξ be a random p vector with uniform (U) distribution on the unit sphere, as in Assumption 5. Let R be a real random variable independent of ξ with distribution $\mu(\cdot)$. Let $\tilde{h} = A(A' \mathscr{I} A)^{-1/2} \xi$. Let $\tilde{Q}(\cdot)$ denote the distribution of \tilde{h} . Note that $\|\tilde{h}\|_{\mathscr{I}} = 1$. Define $h = R\tilde{h}$. Then, $h \sim Q_{\mu}(\cdot)$, as desired.

Using these definitions, (A.16), and $P^{\perp} = AH$, we obtain

(A.17)
$$\overline{PO}_{T}(\mathcal{Q}_{\mu}) = \iint \exp\left[\frac{1}{2}Z'Z - \frac{1}{2}\left(rA(A'\mathscr{I}A)^{-1/2}\xi - AH\overline{\theta}\right)' \\ \times \mathscr{I}\left(rA(A'\mathscr{I}A)^{-1/2}\xi - AH\overline{\theta}\right)\right] dU(\xi) d\mu(r)$$
$$= \iint \exp\left[\frac{1}{2}Z'Z - \frac{1}{2}(r\xi - Z)'(r\xi - Z)\right] dU(\xi) d\mu(r)$$
$$= \int \exp\left[-\frac{1}{2}r^{2}\right] \int \exp\left[\|Z\|r\xi'(Z/\|Z\|)\right] dU(\xi) d\mu(r) = PO(X,\mu),$$

where $X = ||Z||^2$ for two-sided tests and $X = ||Z||^2 \operatorname{sgn}(Z)$ for one-sided tests. The last equality of (A.17) holds by the definitions of $g_p(\kappa)$ and $PO(\cdot, \mu)$.

It remains to show that $||Z||^2 = \overline{W}_T$ for two-sided tests and $||Z||^2 \operatorname{sgn}(Z) = \overline{W}_T$ for one-sided tests. Since $||Z||^2 = (H\bar{\theta})'A' \mathscr{I} A H\bar{\theta}$ and $\operatorname{sgn}(Z) = \operatorname{sgn}(H\bar{\theta})$, the latter results hold provided $A' \mathscr{I} A = (H\mathscr{I}^{-1}H')^{-1}$. By simple algebra, $A' \mathscr{I} A = \mathscr{I}_1 - \mathscr{I}_2 \mathscr{I}_3^{-1} \mathscr{I}_2'$. On the other hand, $(H\mathscr{I}^{-1}H')^{-1}$ equals the inverse of the upper $p \times p$ submatrix of \mathscr{I}^{-1} , which equals $\mathscr{I}_1 - \mathscr{I}_2 \mathscr{I}_3^{-1} \mathscr{I}_2'$ by the formula for a partitioned inverse.

PROOF OF LEMMA A-4: The following assertion is verified below using results of Strasser (1985). If (i) $PO_T(Q_\mu) \stackrel{d}{\to} PO(X, \mu)$ under θ_0 for some random variable X and (ii) $E[PO(X, \mu)] = 1$, then the result of Lemma A-4 holds. Condition (i) is obtained as follows: By Lemmas A-2 and A-3, $PO_T(Q_\mu) - PO(\overline{W}_T, \mu) \stackrel{d}{\to} 0$ under θ_0 . Next, $PO(\overline{W}_T, \mu) \stackrel{d}{\to} PO(X, \mu)$, under θ_0 , where X = Z'Z for two-sided tests, $X = Z^2 \operatorname{sgn}(Z)$ for one-sided tests, and $Z \sim N(0, I_p)$, by Assumptions 1(e) and 2, continuity of $PO(\cdot, \mu)$, and the continuous mapping theorem. Condition (ii) is obtained as follows: For X as above, by (A.17),

(A.18)
$$E[PO(X,\mu)] = E \iint \exp\left[-\frac{1}{2}r^2 + r\xi'Z\right] dU(\xi) d\mu(r)$$
$$= \iint \exp\left[-\frac{1}{2}r^2\right] E \exp\left[r\xi'Z\right] dU(\xi) d\mu(r)$$
$$= \iint \exp\left[-\frac{1}{2}r^2\right] \exp\left[\frac{1}{2}r^2\xi'\xi\right] dU(\xi) d\mu(r) = 1,$$

where the second equality holds by Fubini's Theorem and the third uses the expression for the standard normal moment generating function.

It remains to verify the assertion above. Let (Ω, \mathscr{A}) be a measurable space. Let P_T and Q_T be a null distribution and an alternative distribution on (Ω, \mathscr{A}) for $T \ge 1$. Let $E_T = (\Omega, \mathscr{A}, (P_T, Q_T))$. E_T is called a (binary) *experiment* and $\{E_T: T \ge 1\}$ is a sequence of experiments. One can define equivalent experiments and one can put a metric Δ_2 on the space \mathscr{C}_2/\sim of equivalence classes of experiments; see Strasser (1985, pp. 74, 75). By Theorem 18.11 of Strasser (1985), if $\Delta_2(E_T, E) \to 0$ as $T \to \infty$ for some experiment $E = (\Omega, \mathscr{A}, (P, Q))$, then $\{Q_T: T \ge 1\}$ is contiguous to $\{P_T: T \ge 1\}$ if and only if Q is absolutely continuous with respect to P, i.e., if and only if $\int_0^\infty x\mu_E(dx) = 1$, where μ_E is the distribution of the likelihood ratio dQ/dP under P, $\mathscr{L}(dQ/dP|P)$. Also, by Theorem 16.8 of Strasser (1985), $(\mathscr{C}_2/\sim, \Delta_2)$ and $(\mathscr{M}, \mathscr{F})$ are homeomorphic, where \mathscr{A}

Also, by Theorem 16.8 of Strasser (1985), $(\mathcal{E}_2/\sim, \Delta_2)$ and $(\mathcal{M}, \mathcal{I})$ are homeomorphic, where \mathcal{M} is the set of all probability measures μ on $[0,\infty)$ with $\int_0^\infty x\mu(dx) \leq 1$ and \mathcal{T} is the topology of weak convergence, with homeomorphism T defined by $T(\dot{E}) = \mathcal{L}(dQ/dP/P)$, where \dot{E} is the equivalence class of experiments that contains E and $E = (\Omega, \mathcal{A}, (P, Q))$. In consequence, for any experiment $E = (\Omega, \mathcal{A}, (P, Q))$ and any sequence of experiments $\{E_T: T \geq 1\} = \{(\Omega, A, (P_T, Q_T)): T \geq 1\}, \Delta_2(E_T, E) \to 0$ as $T \to \infty$ if and only if $\mathcal{L}(dQ_T/dP_T|P_T) \Rightarrow \mathcal{L}(dQ/dP|P)$ as $T \to \infty$, where " \Rightarrow " denotes weak convergence (or equivalently, convergence in distribution). This result and the result of the previous paragraph establish the assertion above. Q.E.D.

PROOF OF THEOREM 1: Suppose parts (a)–(c) of Theorem 1 hold under θ_0 . Then, the probability of the set $\{|PO_T(Q_{\mu}) - PO(W_T, \mu)| > \varepsilon\}$ converges to zero as $T \to \infty$ under $\theta_0 \quad \forall \varepsilon > 0$. By contiguity (Lemma A-4), its probability also converges to zero under H_1 . The same holds with W_T replaced by LM_T and LR_T . Thus, it remains to establish parts (a)–(c) of Theorem 1 under θ_0 .

Given Lemmas A-2 and A-3, to establish parts (a)-(c) of Theorem 1 under θ_0 , it suffices to establish (A.4). Since $PO(\cdot, \mu)$ is a continuous function, (A.4) holds if

(A.19) (a)
$$\overline{W}_T - W_T \xrightarrow{p} 0$$
, (b) $W_T - LM_T \xrightarrow{p} 0$, and (c) $LM_T - LR_T \xrightarrow{p} 0$ under θ_0 .

For two-sided tests, part (a) of (A.19) holds because $HT^{1/2}\hat{\theta} - H\bar{\theta} \xrightarrow{p} 0$ under θ_0 by Lemma A-1,

(A.20)
$$\left\| \mathscr{I}_{T}(\hat{\theta}) - \mathscr{I} \right\| \leq \sup_{\theta \in \Theta_{0}} \left\| \mathscr{I}_{T}(\theta) - \mathscr{I}(\theta) \right\| + \left\| \mathscr{I}(\hat{\theta}) - \mathscr{I} \right\| = o_{p}(1),$$

and \mathscr{I} is positive definite (Assumption 1(e)). The inequality in (A.20) holds $wp \rightarrow 1$ using Assumption 3 and the equality in (A.20) holds by Assumptions 1(c), 1(d), and 3. For one-sided tests,

part (a) holds for the above reasons plus the fact that $P(\operatorname{sgn}(H\overline{\theta}) = \operatorname{sgn}(H\widehat{\theta})) \to 1$ under θ_0 , since $H\overline{\theta} - HT^{1/2}\widehat{\theta} \xrightarrow{p} 0$ and $H\overline{\theta} \xrightarrow{d} N(0, H\mathscr{I}^{-1}H')$ under θ_0 . The proofs of parts (b) and (c) are similar to proofs in the literature and, hence, are omitted for brevity. We do point out, however, that for one-sided tests $P(\operatorname{sgn}(H\widehat{\theta}) = \operatorname{sgn}(H\mathscr{I}_T^{-1}(\widehat{\theta})Dl_T(\widehat{\theta}))) \xrightarrow{p} 1$ under θ_0 for the same reasons as for the analogous result in part (a). Q.E.D.

PROOF OF LEMMA 1: Let $\tilde{M} = |M|^{1/2} \operatorname{sgn}(M)$ and $e_1 = (1, 0, \dots, 0)'$. By definitions (2.3) and (2.4),

(A.21)
$$PO(M,\mu) = \iint_{\mathcal{I}_p} \exp\left[-\frac{1}{2}(r\xi)'r\xi + \tilde{M}r\xi'e_1\right] dU(\xi) d\mu(r).$$

Now, in the two-sided case with $R \sim \mu = \sqrt{\tau \chi_p^2}$, we have $R\xi = \omega \sim N(0, \tau I_p)$. We write $\omega = (\omega_1, \tilde{\omega}')'$, where $\omega_1 \in R$ and $\tilde{\omega} \in R^{p-1}$. Then, using (A.21), we obtain

(A.22)
$$PO(M,\mu) = E \exp\left(-\frac{1}{2}\omega'\omega + M\omega_{1}\right)$$
$$= E \exp\left(-\frac{1}{2}\tilde{\omega}'\tilde{\omega}\right) \cdot E \exp\left(-\frac{1}{2}\omega_{1}^{2} + \tilde{M}\omega_{1}\right)$$
$$= (1+\tau)^{-(p-1)/2} \cdot (1+\tau)^{-1/2} \exp\left(\frac{1}{2}\frac{\tau}{1+\tau}M\right),$$

where the last equality holds by rewriting each expectation as a constant times the integral of a normal density over its entire domain.

Next, in the one-sided case with $R \sim \mu = \sqrt{\tau \chi_1^2}$, we have $R\xi \sim |N(0,\tau)|$. Let $\omega \sim N(0,\tau)$ and let $R\xi = |\omega|$. Let $Z \sim N(0,1)$. Then, using (A.21), we have

$$(A.23) \quad PO(M,\mu) = \int_{R} \exp\left[-\frac{1}{2}\omega^{2} + \overline{M}|\omega|\right] (2\tilde{\pi}\tau)^{-1/2} \exp\left[-\frac{1}{2\tau}\omega^{2}\right] d\omega$$

$$= 2\int_{0}^{\infty} (2\tilde{\pi}\tau)^{-1/2} \exp\left[-\frac{1}{2}\left(\frac{1+\tau}{\tau}\omega^{2} - 2\tilde{M}\omega\right)\right] d\omega$$

$$= (1+\tau)^{-1/2} \exp\left[\frac{1}{2}\frac{\tau}{1+\tau}\tilde{M}^{2}\right] 2\int_{0}^{\infty} \left(2\tilde{\pi}\frac{\tau}{1+\tau}\right)^{-1/2}$$

$$\times \exp\left[-\frac{1}{2}\left(\frac{1+\tau}{\tau}\left(\omega - \frac{\tau}{1+\tau}\tilde{M}\right)^{2}\right)\right] d\omega$$

$$= (1+\tau)^{-1/2} \exp\left[\frac{1}{2}\frac{\tau}{1+\tau}M\right] 2P\left(\sqrt{\frac{\tau}{1+\tau}}Z + \frac{\tau}{1+\tau}\tilde{M} > 0\right)$$

$$= (1+\tau)^{-1/2} \exp\left[\frac{1}{2}\frac{\tau}{1+\tau}M\right] 2\Phi\left(\left(\frac{\tau}{1+\tau}|M|\right)^{1/2} \operatorname{sgn}(M)\right). \quad Q.E.D.$$

PROOF OF LEMMA 2: Assumption 1(a) holds by Assumption NL(a). 1(b) holds by NL(c). 1(c) holds with $\mathscr{I}(\theta) = -E\partial^2 \log g_t(\theta)/\partial\theta \,\partial\theta'$ provided a uniform WLLN can be established. The Markov property (NL(b)) ensures that $\{\partial^2 \log g_t(\theta)/\partial\theta \,\partial\theta': t > m\}$ is part of a doubly infinite stationary and ergodic sequence. Thus, using NL(b) and (e), the ergodic theorem implies that $-T^{-1}D^2l_t(\theta) \xrightarrow{\rightarrow} \mathscr{I}(\theta) \,\forall\theta \in \Theta_0$: A generic uniform WLLN (e.g., Assumptions TSE-1D, BD, DM, and P-WLLN and Theorem 4 of Andrews (1992)) strengthens this result to uniform convergence over Θ_0 using NL(b), (c), and (e). Assumption 1(d) holds, because $\mathscr{I}(\theta)$ is continuous on Θ_0 by the dominated convergence theorem using NL(c) and (e) and Θ_0 is compact. 1(e) holds by NL(f).

Note that $\{(\partial \log g_i(\theta_0)/\partial \theta, \mathcal{F}_{i-1}): t > m\}$ is a martingale difference sequence (MDS). Using the Cramer-Wold device, Assumption 2 now follows from the univariate CLT for stationary ergodic square-integrable MDS with positive variances (e.g., see Brown (1971)).

Sufficient conditions for Assumptions 3 are: (i) Θ is compact, (ii) $\log g_t(\theta)$ is continuous in θ on Θ with probability one under θ_0 , (iii) $\sup_{\theta \in \Theta} |(1/T)\Sigma_1^T(\log g_t(\theta) - E \log g_t(\theta)| \xrightarrow{P} 0$ under θ_0 , and (iv) $E \log g_t(\theta)$ is uniquely maximized over Θ at θ_0 (e.g., see Amemiya (1985, Thm. 4.1.1, pp. 106-107)). Parts (i) and (ii) hold by NL(a) and (c) respectively. Part (iii) holds by the same argument as for 1(c) above. To obtain part (iv), note that for $\theta \neq \theta_0$,

(A.24) $E \log g_t(\theta) - E \log g_t(\theta_0) = E \log \left[g_t(\theta) / g_t(\theta_0) \right] < \log E g_t(\theta) / g_t(\theta_0) = 0,$

where the inequality is an application of Jensen's inequality and is strict by NL(d). Assumption 4 holds by the same argument as for Assumption 3 with $\tilde{\Theta}$ in place of Θ . O.E.D.

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